MovementCoordinator

- movement
  - ev_VehicleExited
  - on_foot
    - ev_Move/broadcastEvent(new ev_Run(target))
    - ev_VehicleExited
  - driving
    - ev_VehicleExited
    - ev_VehicleBoarded[vehicle.isDriving()]
    - ev_VehicleBoarded[!vehicle.isDriving()]
    - ev_Drive/broadcastEvent(new ev_Drive(target))
    - ev_DriveComplete/broadcastEvent(new ev_MoveComplete())
    - ev_DriveFailed/broadcastEvent(new ev_MoveFailed())
  - oscillation_lockout
    - startLockoutTimer()
    - ev_VehicleExited
      - ev_VehicleExited[broadcastEvent(new ev_VehicleExited(target))]
      - ev_VehicleBoarded[vehicle.isDriving()]
      - ev_VehicleBoarded[!vehicle.isDriving()]
      - ev_TimerUp
        - ev_VehicleExited
          - ev_VehicleExited[broadcastEvent(new ev_VehicleExited(target))]
          - ev_VehicleBoarded[vehicle.isDriving()]
          - ev_VehicleBoarded[!vehicle.isDriving()]
          - ev_TimerUp